

Statistical analysis of experimental data

Concept of probability

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Lecture 01
October 5, 2023

Concept of probability

- 1 Introduction
- 2 Basic terms
- 3 Definition of Probability
- 4 Properties of Probability
- 5 Bayes' Theorem
- 6 Homework

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It can require building a dedicated experiment (physics, astronomy), preparing survey forms (social sciences) or defining test and control population (medical sciences).

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Statistical analysis is also required for proper experiment design.

It is similarly important for interpretation of “single measurements” ...

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We can easily assure same initial conditions for the repeated measurement...

This is often a fundamental problem in social or medical sciences...

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The knowledge of particle physics is not required (but for some fundamental concepts like the [invariant mass or mean lifetime](#)) and the presented analysis methods can clearly be used also in other fields of science...

Typical problems adapted from book by S.Brandt

- We measure properties of the selected individuals from a large population (could be elementary particles of a given type).

What is the precision of the measurement?

How large the test sample need to be to obtain given precision?

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How large the test sample need to be to obtain given precision?
- A certain experimental result has been obtained. It can be compared with other experiments or with different theoretical predictions.
How to decide, if the results is in agreement with the predicted theoretical value or with previous experiments?
When can we claim that given theoretical model is excluded?

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- A certain experimental result has been obtained. It can be compared with other experiments or with different theoretical predictions.
How to decide, if the results is in agreement with the predicted theoretical value or with previous experiments?
When can we claim that given theoretical model is excluded?
- A general model describing the process studied is known, but parameters of this model must be obtained from experiment (very common case in particle physics).
What is the optimum procedure for extracting model parameters from the data? How can the experiment be optimised to give strongest constraints on the model parameters?

Course plan

14 lectures, Thursdays, 9:15 – 12:00, room B2.38

From October 5th, 2023 to January 25th, 2024

(without November 2!)

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Assessment criteria

Minimum of 50% of points collected from exercises and exam.

Assessment in September: 50% of points from written examination only.

Solutions

Solutions (dedicated files or screenshots of the notebook final output) should be uploaded to Kampus in readable format (PDF, JPG, PNG).

You should not upload the Python notebooks or source codes, please put links to Colab Notebooks files on Google Drive as comments instead! More details to be given next week

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Web resources

Kampus platform will be used for home exercises and final exam:

<https://kampus-student2.ckc.uw.edu.pl/course/view.php?id=14456>

All information, including lecture slides will also be available from the dedicated web page:

<http://www.fuw.edu.pl/~zarnecki/SAED/>

accessible without USOS account...

Some references

- G. Bohm and G. Zech, Introduction to Statistics and Data Analysis for Physicists, Verlag Deutsches Elektronen-Synchrotron, [3rd edition](#);
- S. Brandt, Data Analysis: Statistical and Computational Methods for Scientists and Engineers, Springer 2014;
- **M. Bonamente, Statistics and Analysis of Scientific Data**, Springer 2017;
- R.J. Barlow, Practical Statistics for Particle Physics, [PDF from arXiv](#);
- Max Bramer, Principles of Data Mining, Springer 2016;
- David Forsyth, Probability and Statistics for Computer Science, Springer 2018;
- [Particle Physics Reference Library Volume 2](#) (chapter 15), Springer 2020.

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Experiments

We perform an experiment to collect data.

To allow for statistical analysis we make many measurements...

However, there are always some random factors and results of subsequent measurements are usually different. **It is important to understand where these variations come from!**

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- ① Fluctuations in the measurement results can be due to the actual nature of the physics process studied. Examples: coin toss, roll of a die, but also particle decay time measurement or measurement of source radioactivity...

These fluctuations are unavoidable, we can not reduce them.
But usually this is also the most interesting case for us...

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We can try to reduce the fluctuations (and thus improve precision) by adjusting the measurement procedure...

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Examples: measurement of the drug effectiveness, answers to questionnaires in various types of surveys (eg. asking for age),

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Examples: measurement of the drug effectiveness, answers to questionnaires in various types of surveys (eg. asking for age), mass spectrometry, composition and energy spectra of cosmic rays...

**Results will usually depend on the way the tested population sample is selected.
This selection has to be well defined!**

Experiments

It is crucial to correctly identify the source of fluctuations!

Example: coin diameter measurement.

Fluctuations in numerical results can be due to:

- finite precision of the instrument **there is always some measurement error**
- the measurement method, how we define the diameter **in particular when the coin is not exactly round**
- fluctuations in the actual coin size, **if we measure a set of coins, not a single one**

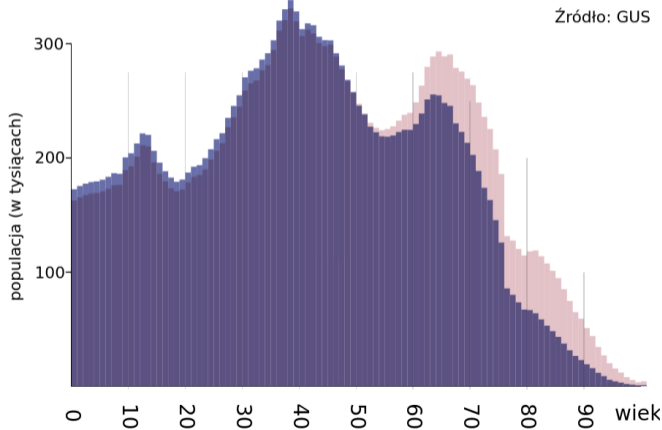
⇒ we need to define the problem properly!

In addition to measurement fluctuations, we also need to consider possible systematic effects.
We will come back to this later...

Experiments

Example: influence of the test sample choice.

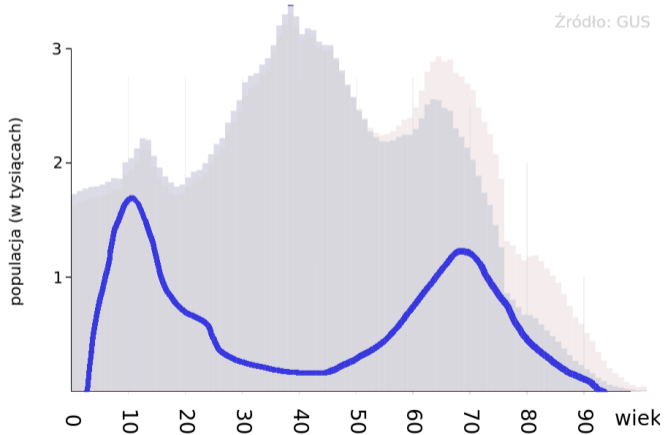
Age structure of the population of Poland (GUS estimate for 2022).



Experiments

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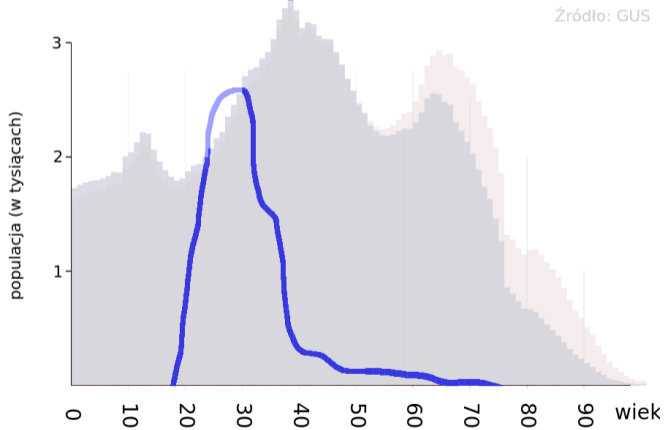
Possible result for survey in public park.



Experiments

Example: influence of the test sample choice.

Possible result for survey at the university campus.



Elementary event

Outcome of a single experiment (measurement):

- result of the roll of a die
- observation of N charged particles in the particle collision
- observation of nuclear decay after given time
- observation of given process, eg. decay $K^+ \rightarrow \mu^+ + \nu_\mu$

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Roll of a die

Six possible outcomes in the sample space: $\Omega = \{1, 2, 3, 4, 5, 6\}$

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Charged particle multiplicity

Particle counting gives non-negative integer number: $\Omega = \{0, 1, 2, \dots\}$

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Decay time measurement

Time interval measured is a real number: $\Omega = \mathbb{R}_+$

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Observation of K^+ decay:

Sample space should include all possible (observable) decay channels:

$$\Omega = \{K^+ \rightarrow \pi^+\pi^0, K^+ \rightarrow \pi^+\pi^0\pi^0, K^+ \rightarrow \pi^+\pi^+\pi^-, K^+ \rightarrow e^+\nu_e, \\ K^+ \rightarrow \mu^+\nu_\mu, K^+ \rightarrow \pi^0e^+\nu_e, K^+ \rightarrow \pi^0\mu^+\nu_\mu, K^+ \rightarrow \pi^0\pi^0e^+\nu_e, \\ K^+ \rightarrow \pi^+\pi^-e^+\nu_e, K^+ \rightarrow \pi^+\mu^+e^-\}$$

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Event

An event A is a given subset of Ω , $A \subset \Omega$,

it can represent a number of possible outcomes for the experiment (!)

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Examples of events

Roll of a die

- six: $A_1 = \{6\}$
- odd number: $A_2 = \{1, 3, 5\}$
- even number: $A_3 = \{2, 4, 6\}$
- any number: $A_4 = \Omega = \{1, 2, 3, 4, 5, 6\}$

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Examples of events

Charged particle multiplicity

- pair production: $A_1 = \{2\}$
- odd number: $A_2 = \{1, 3, 5, \dots\}$
- even number: $A_3 = \{2, 4, 6, \dots\}$

Sample space

Sample space Ω is the set of all possible outcomes of the experiment

Event

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Examples of events

Observation of K^+ decay:

- Hadronic decays

$$A_1 = \{K^+ \rightarrow \pi^+\pi^0, K^+ \rightarrow \pi^+\pi^0\pi^0, K^+ \rightarrow \pi^+\pi^+\pi^-\}$$

- Leptonic decays

$$A_2 = \{K^+ \rightarrow e^+\nu_e, K^+ \rightarrow \mu^+\nu_\mu\}$$

- LFV decay (forbidden in SM)

$$A_3 = \{K^+ \rightarrow \pi^+\mu^+e^-\}$$

Events

From the formal point of view it is useful to introduce two events which exist for each experiment:

- impossible (empty) event: $A = \emptyset$
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We also define:

- union of events $C = A \cup B$: all outcomes belonging to A or B
- intersection of events $D = A \cap B$: all outcomes belonging to A and B
- complementary event $E = \bar{A}$: all outcomes not belonging to A
- mutually exclusive events: two events with no common outcome
 \Rightarrow their intersection is an empty event: $A \cap B = \emptyset$

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We do have an intuitive understanding of the probability concept...

Probability $P(A)$ of an event A should describes the odds of an outcome of single measurement (experiment) to belong to A

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Classical definition as developed in the 18th–19th centuries

If the sample space contains N_Ω elementary events (possible outcomes of the experiment) and the considered event A contains N_A elementary events, then, assuming all elementary events are equally probable

$$P(A) = \frac{N_A}{N_\Omega}$$

Classical definition - example

see also in [Wikipedia](#)

In a straight poker game, consider player dealing five cards from a deck of 52.

Sampling space contains all possible “hands”, all possible sets of 5 cards selected out of 52

(order is not relevant):

$$N_{\Omega} = \binom{52}{5} = 2\,598\,960$$

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We have four suits and the sequence can start from 9 numbers (from 1 to 9):

$$N_{flush} = 4 \times 9 = 36 \Rightarrow p_{flush} = \frac{36}{2\,598\,960} \approx 1.35 \cdot 10^{-5}$$

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What is the probability to get four cards of the same rank?

$$N_{four} = 13 \times 48 = 624 \Rightarrow p_{four} = \frac{624}{2\,598\,960} \approx 2.4 \cdot 10^{-4}$$

where we had to take into account the number of fifth card options (48)...

Classical definition

The classical definition of the probability works fine in many simple problems, the gambling games in particular.

However, the sampling space and elementary events have to be uniquely defined!

This is usually not a problem for experimental results given by discrete numbers (eg. roll of a die, card games, etc.).

But problems arise when this approach is to be applied to experiments with continuous spectra of possible measurement results...

This is well illustrated by the “Bertrand paradox”

Bertrand paradox

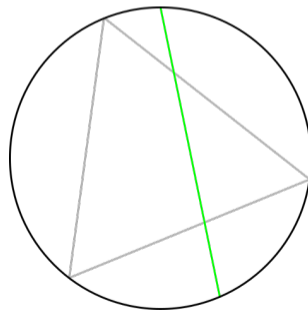
description adapted from R. J. Barlow
pictures from Wikipedia

Definition of the problem:

In a circle of radius R an equilateral triangle is drawn.

What is the probability that the length of a **random chord** is greater than the triangle side?

How the random chord should be defined?



Bertrand paradox

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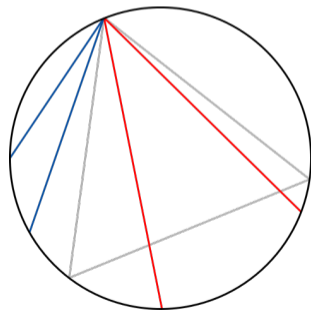
What is the probability that the length of a **random chord** is greater than the triangle side?

Solution 1:

A random chord can be defined as connecting two random points on the circle.

Without loss of generality, we can move one of its ends to the vertex of the triangle.

The chord will be longer than the side of the triangle, if its other end is between the two other vertices \Rightarrow **probability is $1/3$** .



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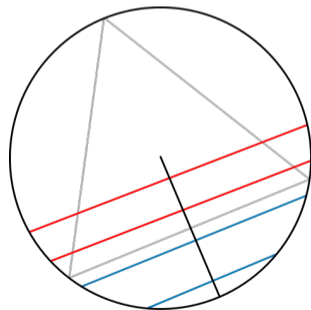
What is the probability that the length of a **random chord** is greater than the triangle side?

Solution 2:

Without loss of generality, we can rotate a random chord in such a way that its centre is on the indicated radius of the circle.

The chord will be longer than the side of the triangle, if its centre is inside the triangle.

The side of the triangle cuts the radius in the middle \Rightarrow probability is $1/2$.



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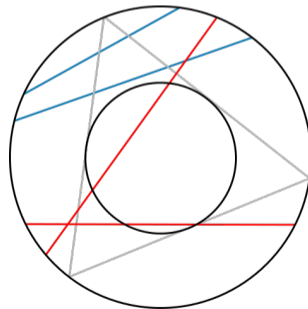
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Solution 3:

Without loss of generality, the centre of the chord can be chosen at random in the circle.

The chord will be longer than the side of the triangle, if its centre is inside the circle of radius $R/2$.

The surface of the circle is proportional to radius squared \Rightarrow probability is $1/4$.



Bertrand paradox

Base on the classical probability definition, we can get three contradictory answers to the problem. In the considered continuous sample space

“equally probable” elementary events are not uniquely defined!

We need to define how the actual experiment is performed...

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Frequentist definition of probability

When repeating the same experiment a large number of times, $N \gg 1$, the probability of A

$$P(A) = \lim_{N \rightarrow \infty} \frac{N(A)}{N}$$

where $N(A)$ is the number of occurrences of the event A

While this is not visible in the formula, the probability still depends on the considered sample space Ω , which reflects the way the experiment is done.

The frequentist (sometimes also called “classical”) definition of probability gives direct recipe for the analysis of experimental data...

However, it is not always possible to perform the experiment a very large (infinite) number of times... We need some additional guidance to know how to define the probability.

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Kolmogorov Axioms

Kolmogorov (1933) formulated the three conditions which have to be fulfilled by probability $P(A)$ of an event $A \subset \Omega$:

- 1 probability is a non-negative number: $P(A) \geq 0$
- 2 probability of all possible outcomes (sample space): $P(\Omega) = 1$
- 3 if A and B are mutually exclusive events: $P(A \cup B) = P(A) + P(B)$

We can derive all properties of the probability from these three axioms...

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Fundamental properties

Following properties can be derived from the Kolmogorov axioms:

- probability of the empty event is zero:

$$P(\emptyset) = 0$$

\emptyset and Ω are mutually exclusive and $\Omega = \Omega \cup \emptyset$

$$\Rightarrow P(\Omega) = P(\Omega) + P(\emptyset) \quad \Rightarrow P(\emptyset) = 0$$

Fundamental properties

Following properties can be derived from the Kolmogorov axioms:

- probability of the empty event is zero:

$$P(\emptyset) = 0$$

- probability of complementary event:

$$P(\bar{A}) = 1 - P(A)$$

A and \bar{A} are mutually exclusive and by definition $A \cup \bar{A} = \Omega$
 $\Rightarrow P(A) + P(\bar{A}) = P(\Omega) = 1 \quad \Rightarrow P(\bar{A}) = 1 - P(A)$

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- probability of the empty event is zero:

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- probability of complementary event:

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- probability of the union of two events:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

Union of A and B can be decomposed as:

$$P(A \cup B) = P(A \cap \bar{B}) + P(B \cap \bar{A}) + P(A \cap B)$$

Fundamental properties

Following properties can be derived from the Kolmogorov axioms:

- probability of the empty event is zero:

$$P(\emptyset) = 0$$

- probability of complementary event:

$$P(\bar{A}) = 1 - P(A)$$

- probability of the union of two events:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

and then one can note that

$$P(A \cap \bar{B}) = P(A) - P(A \cap B) \quad \text{and} \quad P(B \cap \bar{A}) = P(B) - P(B \cap A)$$

Statistical Independence

Two events A and B are said to be statistically independent if and only if

$$P(A \cap B) = P(A) \cdot P(B)$$

Two important properties follow:

- mutually exclusive (nonempty) events cannot be independent
- if A is subset of B , $A \subset B$, they cannot be independent, unless $B = \Omega$

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Conditional Probability

When two events are **not independent**, we can consider probability of event A given that another event B is observed:

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \quad \text{or } 0 \text{ if } P(B) = 0$$

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For independent events: $P(A|B) = P(A)$

Example (1)

Rolling a single die: $N = 6$ possible outcomes (elementary events).

We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = 1/6$

Consider following events:

- odd number: $A_1 = \{1, 3, 5\}$ $\Rightarrow p_1 = 1/2$
- even number: $A_2 = \{2, 4, 6\}$ $\Rightarrow p_2 = 1/2$
- 1 or 6: $A_3 = \{1, 6\}$ $\Rightarrow p_3 = 1/3$
- at least 4: $A_4 = \{4, 5, 6\}$ $\Rightarrow p_4 = 1/2$

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A_1 and A_2 are not independent, they are mutually exclusive:

$$P(A_1 \cap A_2) = P(\emptyset) = 0$$

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A_1 and A_3 are independent:

$$A_1 \cap A_3 = \{1\}$$

$$P(A_1 \cap A_3) = p_e = 1/6 = P(A_1) \cdot P(A_3)$$

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- at least 4: $A_4 = \{4, 5, 6\} \Rightarrow p_4 = 1/2$

A_1 and A_4 are **NOT** independent:

$$A_1 \cap A_4 = \{5\}$$

$$P(A_1 \cap A_4) = p_e = 1/6 \neq P(A_1) \cdot P(A_4) = 1/4$$

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Probability of A_4 when A_1 is observed:

$$P(A_4|A_1) = \frac{P(A_1 \cap A_4)}{P(A_1)} = \frac{1/6}{1/2} = 1/3 \neq P(A_4)$$

Example (2)

Rolling two dice (eg. red and blue): $N = 6 \cdot 6 = 36$ possible outcomes.

Sample space can be best presented as a table:

	1	2	3	4	5	6
1						
2						
3						
4						
5						
6						

We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = \frac{1}{36}$

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	1	2	3	4	5	6
1			A			B
2			A		B	
3			A	B		
4			$A \cap B$			
5		B	A			
6	B		A			

We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = \frac{1}{36}$

Events: A - red die shows 3 and B - sum of two dice is 7

$$P(A \cap B) = 1/36 = P(A) \cdot P(B) \quad \Rightarrow \text{are independent}$$

Example (2)

Rolling two dice (eg. red and blue): $N = 6 \cdot 6 = 36$ possible outcomes.

Sample space can be best presented as a table:

	1	2	3	4	5	6
1			A	C		
2			$A \cap C$			
3		C	A			
4	C		A			
5			A			
6			A			

We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = \frac{1}{36}$

Events: A - red die shows 3 and C - sum of two dice is 5

$$P(A \cap C) = 1/36 \neq P(A) \cdot P(C) = 1/6 \cdot 1/9 \Rightarrow \text{NOT independent}$$

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	1	2	3	4	5	6
1			A	C		
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3		C	A			
4	C		A			
5			A			
6			A			

We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = \frac{1}{36}$

Events: A - red die shows 3 and C - sum of two dice is 5

$$P(A|C) = P(A \cap C)/P(C) = \frac{1}{36} / \frac{1}{9} = 1/4$$

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5			A			
6			A			

We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = \frac{1}{36}$

Events: A - red die shows 3 and C - sum of two dice is 5

$$P(C|A) = P(A \cap C)/P(A) = \frac{1}{36} / \frac{1}{6} = 1/6$$

Partition of the sample space

It is a set of events A_i ($i = 1 \dots n$) with the following properties:

- all A_i are mutually exclusive

$$A_i \cap A_j = \emptyset, \quad \forall i \neq j$$

- they cover the whole sampling space

$$\bigcup_{i=1}^n A_i = \Omega$$

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- they cover the whole sampling space

$$\bigcup_{i=1}^n A_i = \Omega$$

From the two conditions we realize that:

$$\sum_{i=1}^n P(A_i) = 1$$

We can be sure that one (and only one) A_i will always take place

Concept of probability

- 1 Introduction
- 2 Basic terms
- 3 Definition of Probability
- 4 Properties of Probability
- 5 Bayes' Theorem**
- 6 Homework

Total Probability Theorem

Given partition A_i of the sampling space, for any event B we can write

$$P(B) = \sum_{i=1}^n P(B \cap A_i) = \sum_{i=1}^n P(B|A_i) \cdot P(A_i)$$

Total probability of B can be calculated as a sum over probabilities calculated in separate sub-spaces. Very useful in many cases...

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Example (1)

What is the probability of giving birth to twins in Europe?

We can address this problem by combining probabilities for different countries in Europe:

$$P(\text{Twins}) = \sum_{i=1}^n P(\text{Twins}|\text{Country}_i) \cdot \frac{N_i}{\sum_{i=1}^n N_i}$$

where N_i is the number of all births in country i

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Total probability of B can be calculated as a sum over probabilities calculated in separate sub-spaces. Very useful in many cases...

Example (2)

What is the probability of producing π^+ in e^+e^- annihilation into Z^0 :

$$e^+e^- \rightarrow Z^0 \rightarrow \pi^+ + \dots$$

We can divide the sampling space, **all Z^0 decays**, into separate decay channels, $Z^0 \rightarrow f\bar{f}$, where $f = e, \mu, \tau, \nu_e, \nu_\mu, \nu_\tau, u, d, s, c, b$. For some of these channels the answer is known.

eg. $P(\pi^+ | Z \rightarrow \nu\bar{\nu}) = 0$

Bayes' Theorem

For events A and B the two conditional probabilities are related:

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \quad \text{and} \quad P(B|A) = \frac{P(B \cap A)}{P(A)}$$

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This can be also written in a more general form:

$$P(A_i|B) = \frac{P(B|A_i) P(A_i)}{\sum_{j=1}^n P(B|A_j) P(A_j)}$$

where A_j is the partition of the sampling space.

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where A_j is the partition of the sampling space.

There is nothing new in this as long as A_j and B belong to the same sampling space...

Bayesian approach

Bayes theorem can be used to generalize the concept of probability.

In particular, one can consider “probability” of given hypothesis H

(theoretical model or model parameter, eg. Hubble constant)

when taking into known outcome D (data) of the experiment:

$$P(H|D) = \frac{P(D|H)}{P(D)} \cdot P(H)$$

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There are two problems with this approach:

- H can not be considered an event, sampling space can not be defined (no experiment to repeat)
- we need to make a **subjective** assumption about the “prior” $P(H)$ describing our initial belief in hypothesis H

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For these reasons I rather use term “degree of belief” for the result of the Bayesian procedure applied to non random events

Example of Bayesian approach

adapted from G. Cowan, 2011 CERN Summer Student Lectures on Statistics

How much should I worry, if I get a positive Covid test result?

- Hypothesis: H - I have covid
- Data: D - test result is positive

How likely is it that I have covid, what is $P(H|D)$?

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How likely is it that I have covid, what is $P(H|D)$?

We need to know efficiency and false rate for the test. Let us assume

$$P(D|H) = 0.99 \quad \text{test efficiency}$$

$$P(D|\bar{H}) = 0.01 \quad \text{false positive rate}$$

We can also assume that 1 person per 1000 infected in our country

$$P(H) = 0.001$$

Example of Bayesian approach

We first use the total probability theorem to calculate the probability of the positive test result, $P(D)$:

$$\begin{aligned}P(D) &= P(D|H) \cdot P(H) + P(D|\bar{H}) \cdot P(\bar{H}) \\ &= 0.99 \cdot 0.001 + 0.01 \cdot 0.999 = 0.01098 \approx 0.011\end{aligned}$$

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and then apply Bayes' theorem:

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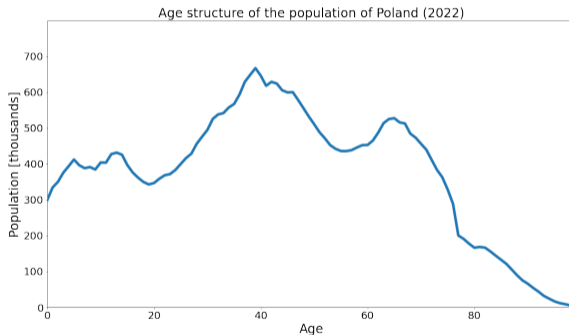
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You can believe that your chances of being infected with covid are 9%.
How useful is this information in your opinion?

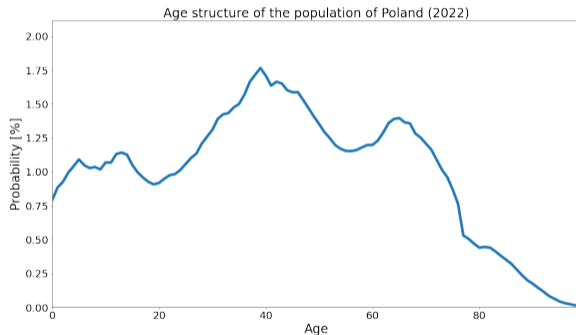
Prior problem

Let us look again at the statistical data on the population of Poland:



Prior problem

Let us look again at the statistical data on the population of Poland:



We can present it as the age probability (for randomly chosen person).

Can we draw any conclusions concerning the life expectation?

Prior problem

To simplify the problem, let us assume that the “survival probability” does not change in time:

$$p(y|b) = s(a)$$

where: b is the year of birth, y is the year of the population census, $a = y - b$ is age.

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Unfortunately, what we measure is the age distribution:

$$p(a) = p(b|y) \quad \text{for } b = y - a$$

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Unfortunately, what we measure is the age distribution:

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We can apply Bayes' Theorem to relate it to the “survival probability”

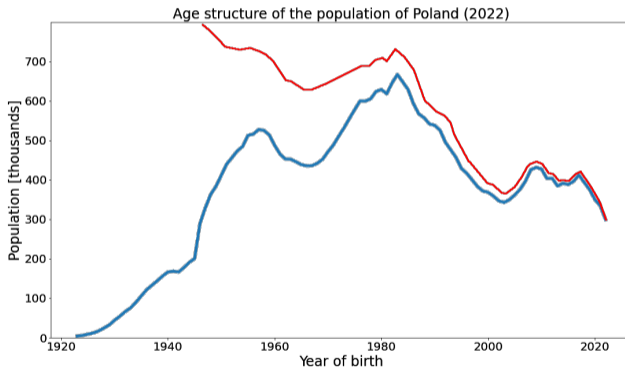
$$p(a) = \frac{s(a) \cdot u(y - a)}{\sum_b s(y - b) \cdot u(b)}$$

where $u(b)$ is the birth number distribution. **We need to know it!!!**

Prior problem

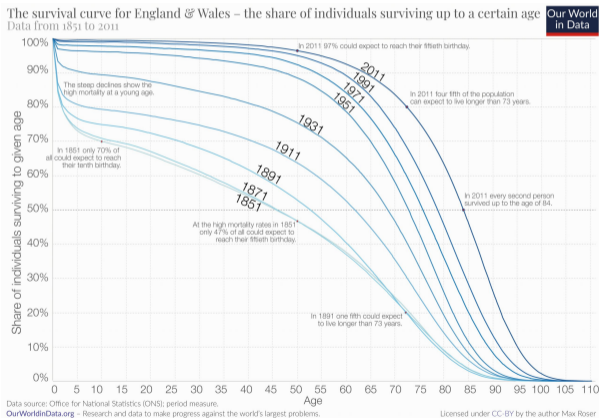
What is needed is the number of births in each year:

shown is my guess



Without exact knowledge of this “prior” we can not draw any conclusions...

There are also other reasons, why extraction of survival curve from single population census is not possible. In particular, it depends significantly on the year of birth...



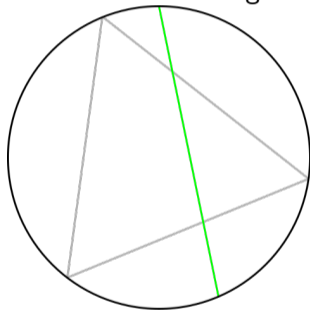
Source: ourworldindata.org

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Bertrand paradox

In a circle of radius R an equilateral triangle is drawn. What is the probability that the length of a **random chord** is greater than the side of the triangle?



What is, in your opinion, the correct answer to the problem?

Give arguments for the proper construction of random chord.

You can also propose your own definition/construction!

Solutions should be
uploaded until October 19.