Statistical analysis of experimental data Concept of probability

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Lecture 01 October 3, 2024

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It can require building a dedicated experiment (physics, astronomy), preparing survey forms (social sciences) or defining test and control population (medical sciences).

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Statistical analysis is also required for proper experiment design. It is similarly important for interpretation of "single measurements"...

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The knowledge of particle physics is not required (but for some fundamental concepts like the invariant mass or mean lifetime) and the presented analysis methods can clearly be used also in other fields of science. \blacksquare

Typical problems adapted from book by S.Brandt

We measure properties of the selected individuals from a large population (could be elementary particles of a given type). What is the precision of the measurement? How large the test sample need to be to obtain given precision?

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- We measure properties of the selected individuals from a large population (could be elementary particles of a given type). What is the precision of the measurement? How large the test sample need to be to obtain given precision?
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- We measure properties of the selected individuals from a large population (could be elementary particles of a given type). What is the precision of the measurement? How large the test sample need to be to obtain given precision?
- A certain experimental result has been obtained. It can be compared with other experiments or with different theoretical predictions. How to decide, if the results is in agreement with the predicted theoretical value or with previous experiments? When can we claim that given theoretical model is excluded?
- A general model describing the process studied is known, but parameters of this model must be obtained from experiment (very common case in particle physics). What is the optimum procedure for extracting model parameters from the data? How can the experiment be optimised to give strongest constraints on the model parameters?

Course plan

14 lectures, Thursdays, 9:15 – 12:00, room B2.38 From October 3th, 2024 to January 23th, 2025 (without January 9th!)

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Assessment criteria

Minimum of 50% of points collected from exercises and exam (with the same weight). Assessment in September: 50% of points from written examination only.

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Solutions

Solutions (dedicated files or printouts of the notebook with the final output) should be uploaded to Kampus in readable format (PDF preferred).

Upload the Python notebook or add the link to your notebook in Google Colab as a comment! Please share your Google Colab space with a.zarneckiuw.edu.pl, so I can access your notebook. More details to be given next week

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Web resources

Kampus platform will be used for home exercises and final exam: <https://kampus-kursy.ckc.uw.edu.pl/course/view.php?id=802>

All information, including lecture slides will also be available from the dedicated web page:

<http://www.fuw.edu.pl/~zarnecki/SAED/>

accessible without USOS account...

Some references

- G. Bohm and G. Zech, Introduction to Statistics and Data Analysis for Physicsts, Verlag Deutsches Elektronen-Synchrotron, [3rd edition;](https://bib-pubdb1.desy.de/record/389738)
- S. Brandt, Data Analysis: Statistical and Computational Methods for Scientists and Engineers, Springer 2014;
- M. Bonamente, Statistics and Analysis of Scientific Data, Springer 2017;
- R.J. Barlow, Practical Statistics for Particle Physics, [PDF from arXiv;](https://arxiv.org/pdf/1905.12362)
- Max Bramer, Principles of Data Mining, Springer 2016;
- **David Forsyth, Probability and Statistics for Computer Science, Springer 2018;**
- [Particle Physics Reference Library Volume 2](https://link.springer.com/book/10.1007/978-3-030-35318-6) (chapter 15), Springer 2020.

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To allow for statistical analysis we make many measurements...

However, there are always some random factors and results of subsequent measurements are usually different. It is important to understand where these variations come from!

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These fluctuations are unavoidable, we can not reduce them. But usually this is also the most interesting case for us...

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We can try to reduce the fluctuations (and thus improve precision) by adjusting the measurement procedure...

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Results will usually depend on the way the tested population sample is selected. This selection has to be well defined!

It is crucial to correctly identify the source of fluctuations!

Example: coin diameter measurement.

Fluctuations in numerical results can be due to:

- **•** finite precision of the instrument there is always some measurement error
- **•** the measurement method, how we define the diameter in particular when the coin is not exactly round
- \bullet fluctuations in the actual coin size.

if we measure a set of coins, not a single one

 \Rightarrow we need to define the problem properly!

In addition to measurement fluctuations, we also need to consider possible systematic effects. We will come back to this later...

Experiments Example: influence of the test sample choice.

Age structure of the population of Poland (GUS estimate for 2022).

Experiments Example: influence of the test sample choice.

Possible result for survey in public park (on working day).

Experiments Example: influence of the test sample choice.

Possible result for survey at the university campus.

Outcome of a single experiment (measurement):

- result of the roll of a die
- observation of N charged particles in the particle collision
- observation of nuclear decay after given time
- observation of given process, eg. decay $\mathcal{K}^+ \rightarrow \mu^+ + \nu_\mu$

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Roll of a die

Six possible outcomes in the sample space: $\Omega = \{1, 2, 3, 4, 5, 6\}$

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Charged particle multiplicity

Particle counting gives non-negative integer number: $\Omega = \{0, 1, 2, \ldots\}$

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Decay time measurement

Time interval measured is a real number: $\Omega = \mathbb{R}_+$

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Observation of K^+ decay:

Sample space should include all possible (observable) decay channels:

$$
\Omega=\{K^+\to\pi^+\pi^{\circ},K^+\to\pi^+\pi^{\circ}\pi^{\circ},K^+\to\pi^+\pi^+\pi^-, \quad K^+\to e^+\nu_e, K^+\to\mu^+\nu_{\mu},
$$

 $\mathsf{K}^+ \to \pi^{\circ} \mathrm{e}^+ \nu_{\mathrm{e}}, \mathsf{K}^+ \to \pi^{\circ} \mu^+ \nu_{\mu}, \mathsf{K}^+ \to \pi^{\circ} \pi^{\circ} \mathrm{e}^+ \nu_{\mathrm{e}}, \mathsf{K}^+ \to \pi^+ \pi^- \mathrm{e}^+ \nu_{\mathrm{e}}, \quad \mathsf{K}^+ \to \pi^+ \mu^+ \mathrm{e}^- \}$

Sample space Ω is the set of all possible outcomes of the experiment

Event

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An event A is a given subset of \Omega, A \subset \Omega,
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Examples of events

Roll of a die

- six: $A_1 = \{6\}$
- odd number: $A_2 = \{1, 3, 5\}$
- even number: $A_3 = \{2, 4, 6\}$
- any number: $A_4 = \Omega = \{1, 2, 3, 4, 5, 6\}$

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Examples of events

Charged particle multiplicity

- pair production: $A_1 = \{2\}$
- odd number: $A_2 = \{1, 3, 5, ...\}$
- even number: $A_3 = \{2, 4, 6, ...\}$

Sample space Ω is the set of all possible outcomes of the experiment

Event

```
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```
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Examples of events Observation of K^+ decay:

• Hadronic decays

$$
A_1=\{K^+\rightarrow\pi^+\pi^\circ,K^+\rightarrow\pi^+\pi^\circ\pi^\circ,K^+\rightarrow\pi^+\pi^+\pi^-\}
$$

• Leptonic decays

$$
A_2 = \{K^+ \to e^+ \nu_e, K^+ \to \mu^+ \nu_\mu\}
$$

LFV decay (forbidden in SM)

$$
A_3=\{K^+\rightarrow\pi^+\mu^+e^-\}
$$

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- impossible (empty) event: $A = \emptyset$
- sure event: $A = \Omega$

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- intersection of events $D = A \cap B$: all outcomes belonging to A and B
- complementary event $E = \overline{A}$: all outcomes not belonging to A
- mutually exclusive events: two events with no common outcome
	- \Rightarrow their intersection is an empty event: $A \cap B = \emptyset$

Concept of probability

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How to define probability?

We do have an intuitive understanding of the probability concept...

Probability $P(A)$ of an event A should describes the odds of an outcome of single measurement (experiment) to belong to A

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Classical definition as developed in the 18th–19th centuries

If the sample space contains N_{Ω} elementary events (possible outcomes of the experiment) and the considered event A contains N_A elementary events, then, **assuming all elementary** events are equally probable

$$
P(A) = \frac{N_A}{N_{\Omega}}
$$

In a straight poker game, consider player dealing five cards from a deck of 52. Sampling space contains all possible "hands", all possible sets of 5 cards selected out of 52 (order is not relevant):

 $N_{\Omega} = \begin{pmatrix} 52 \\ 52 \end{pmatrix}$ 5 $= 2598960$

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$$
\begin{array}{c}\n \hline\n \text{S}\n \end{array}
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\nWhat is the probability of a "straight flush" (five cards in a sequence, of the same suit)?

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$$
\begin{array}{c}\n \hline\n \text{1} & 5 \\
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\nWhat is the probability of a "straight flush" (five cards in a sequence, of the same suit)?

\nWe have four suits and the sequence can start from 9 numbers (from 1 to 9):

$$
N_{\text{flush}} = 4 \times 9 = 36 \Rightarrow \quad p_{\text{flush}} = \frac{36}{2598\,960} \approx 1.35 \cdot 10^{-5}
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What is the probability of a "straight flush" (five cards in a sequence, of the same suit)? We have four suits and the sequence can start from 9 numbers (from 1 to 9):
$$
f(x) = \frac{1}{2} \int_{-\infty}^{\infty} f(x) \, dx
$$

5

$$
N_{\text{flush}} = 4 \times 9 = 36 \Rightarrow \quad p_{\text{flush}} = \frac{36}{2598960} \approx 1.35 \cdot 10^{-5}
$$

What is the probability to get four cards of the same rank?

$$
N_{four} = 13 \times 48 = 624 \Rightarrow p_{four} = \frac{624}{2598960} \approx 2.4 \cdot 10^{-4}
$$

where we had to take into account the number of options (48) for the fifth card !

Classical definition

The classical definition of the probability works fine in many simple problems, the gambling games in particular.

However, the sampling space and elementary events have to be uniquely defined!

This is usually not a problem for experimental results given by discrete numbers (eg. roll of a die, card games, etc.).

But problems arise when this approach is to be applied to experiments with continuous spectra of possible measurement results...

This is well illustrated by the "Bertrand paradox"

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In a circle of radius R an equilateral triangle is drawn.

What is the probability that the length of a random chord is greater than the triangle side?

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The problem seems to be simple, but we realize that the main question is: how the random chord should be defined?

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Solution 1:

A random chord can be defined as a line connecting two random points on the circle.

Without loss of generality, we can move one of its ends to the vertex of the triangle.

The chord will be longer than the side of the triangle, if its other end is between the two other vertices \Rightarrow probability is 1/3

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Solution 2:

Without loss of generality, we can rotate a random chord in such a way that its centre is on the indicated radius of the circle.

The chord will be longer than the side of the triangle, if its centre is inside the triangle.

The side of the triangle cuts the radius in the middle

 \Rightarrow probability is 1/2

Definition of the problem:

In a circle of radius R an equilateral triangle is drawn.

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Solution 3:

We can draw a chord by choosing a random point in the circle as its centre (unique definition of the chord).

The chord will be longer than the side of the triangle, if its centre is inside the circle of radius $R/2$.

The surface of the circle is proportional to radius squared

 \Rightarrow probability is 1/4.

Bertrand paradox

Base on the classical probability definition, we can get three contradictory answers! Why?

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In the considered continuous sample space

"equally probable" elementary events are not uniquely defined!

We need to define how the actual experiment is performed...

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Frequentist definition of probability

When repeating the same experiment a large number of times, $N \gg 1$, the probability of A

$$
P(A) = \lim_{N \to \infty} \frac{N(A)}{N}
$$

where $N(A)$ is the number of occurrences of the event A While this is not visible in the formula, the probability still depends on the considered sample space Ω , which reflects the way the experiment is done.

Definition of Probability

The frequentist (sometimes also called "classical") definition of probability gives direct recipe for the analysis of experimental data...

However, it is not always possible to perform the experiment a very large (infinite) number of times... We need some additional guidance to know how to define the probability.

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Kolmogorov Axioms

Kolmogorov (1933) formulated the three conditions which have to be fulfilled by probability $P(A)$ of an event $A \subset \Omega$:

- **1** probability is a non-negative number: $P(A) > 0$
- 2 probability of all possible outcomes (sample space): $P(\Omega) = 1$
- **3** if A and B are mutually exclusive events: $P(A \cup B) = P(A) + P(B)$

We can derive all properties of the probability from these three axioms...

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Fundamental properties

Following properties can be derived from the Kolmogorov axioms:

• probability of the empty event is zero:

 $P(\emptyset) = 0$

 \emptyset and Ω are mutually exclusive and $\Omega = \Omega \cup \emptyset$ $\Rightarrow P(\Omega) = P(\Omega) + P(\emptyset) \Rightarrow P(\emptyset) = 0$

Fundamental properties

Following properties can be derived from the Kolmogorov axioms:

• probability of the empty event is zero:

$$
P(\emptyset)=0
$$

• probability of complementary event:

$$
P(\bar{A})=1-P(A)
$$

A and \bar{A} are mutually exclusive and by definition $A \cup \bar{A} = \Omega$ $\Rightarrow P(A) + P(\overline{A}) = P(\Omega) = 1 \Rightarrow P(\overline{A}) = 1 - P(A)$

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• probability of the union of two events:

$$
P(A \cup B) = P(A) + P(B) - P(A \cap B)
$$

Union of A and B can be decomposed as:

$$
P(A \cup B) = P(A \cap \overline{B}) + P(B \cap \overline{A}) + P(A \cap B)
$$

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P(\emptyset)=0
$$

• probability of complementary event:

$$
P(\bar{A})=1-P(A)
$$

• probability of the union of two events:

$$
P(A \cup B) = P(A) + P(B) - P(A \cap B)
$$

and then one can note that

 $P(A \cap \overline{B}) = P(A) - P(A \cap B)$ and $P(B \cap \overline{A}) = P(B) - P(B \cap A)$

Statistical Independence

Two events A and B are said to be statistically independent if and only if

 $P(A \cap B) = P(A) \cdot P(B)$

Two important properties follow:

- mutually exclusive (nonempty) events cannot be independent
- if A is subset of B, $A \subset B$, they cannot be independent, unless $B = \Omega$

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Conditional Probability

When two events are not independent, we can consider probability of event A given that another event B is observed:

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P(A|B) = \frac{P(A \cap B)}{P(B)} \quad \text{or } 0 \text{ if } P(B) = 0
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For independent events: $P(A|B) = P(A)$

Rolling a single die: $N = 6$ possible outcomes (elementary events). We assume each outcome has the same probability $\Rightarrow p_e = P(\Omega)/N = 1/6$

Consider following events:

• odd number: $A_1 = \{1, 3, 5\}$ • even number: $A_2 = \{2, 4, 6\}$ • 1 or 6: $A_3 = \{1, 6\}$ • at least 4: $A_4 = \{4, 5, 6\}$ \Rightarrow $p_1 = 1/2$ \Rightarrow $p_2 = 1/2$ \Rightarrow $p_3 = 1/3$ \Rightarrow $p_4 = 1/2$

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 A_1 and A_2 are not independent, they are mutually exclusive:

 $P(A_1 \cap A_2) = P(\emptyset) = 0$

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 A_1 and A_3 are independent:

 $A_1 \cap A_3 = \{1\}$ $P(A_1 \cap A_3) = p_e = 1/6 = P(A_1) \cdot P(A_3)$

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 A_1 and A_4 are NOT independent:

 $A_1 \cap A_4 = \{5\}$ $P(A_1 \cap A_4) = p_e = 1/6 \neq P(A_1) \cdot P(A_4) = 1/4$

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Probability of A_4 when A_1 is observed:

$$
P(A_1 \cap A_4) = 1/6
$$

$$
P(A_4|A_1) = \frac{P(A_1 \cap A_4)}{P(A_1)} = \frac{1/6}{1/2} = 1/3 \neq P(A_4)
$$

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Rolling two dice (eg. red and blue): $N = 6 \cdot 6 = 36$ possible outcomes. Sample space can be best presented as a table:

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We assume each outcome has the same probability $\Rightarrow p_{\text{e}} = P(\Omega)/N = \frac{1}{36}$ 36 Events: $A - red$ die shows 3 and $B - sum$ of two dice is 7

 $P(A \cap B) = 1/36 = P(A) \cdot P(B)$ \Rightarrow are independent

Rolling two dice (eg. red and blue): $N = 6 \cdot 6 = 36$ possible outcomes. Sample space can be best presented as a table:

We assume each outcome has the same probability $\Rightarrow p_{\text{e}} = P(\Omega)/N = \frac{1}{36}$ 36 Events: $A - red$ die shows 3 and $C - sum$ of two dice is 5

 $P(A \cap C) = 1/36 \neq P(A) \cdot P(C) = 1/6 \cdot 1/9 \Rightarrow$ NOT independent

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 $P(A|C) = P(A \cap C)/P(C) = \frac{1}{36}/\frac{1}{9} = 1/4$

Rolling two dice (eg. red and blue): $N = 6 \cdot 6 = 36$ possible outcomes. Sample space can be best presented as a table:

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 $P(C|A) = P(A \cap C)/P(A) = \frac{1}{36} / \frac{1}{6} = 1/6$

Partition of the sample space

It is a set of events A_i $(i = 1 \ldots n)$ with the following properties:

• all A_i are mutually exclusive

$$
A_i \cap A_j = \emptyset, \qquad \forall i \neq j
$$

• they cover the whole sampling space

$$
\bigcup_{i=1}^n A_i = \Omega
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\bigcup_{i=1}^n A_i = \Omega
$$

From the two conditions we realize that:

$$
\sum_{i=1}^n P(A_i) = 1
$$

We can be sure that one (and only one) A_i will always take place

Concept of probability

- **[Introduction](#page-2-0)**
- **[Basic terms](#page-22-0)**
- [Definition of Probability](#page-51-0)
- 4 [Properties of Probability](#page-70-0)
- 5 [Bayes' Theorem](#page-90-0)

[Homework](#page-114-0)

Total Probability Theorem

Given partition A_i of the sampling space, for any event B we can write

$$
P(B) = \sum_{i=1}^{n} P(B \cap A_i) = \sum_{i=1}^{n} P(B|A_i) \cdot P(A_i)
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Total probability of B can be calculated as a sum over probabilities calculated in separate sub-spaces. Very useful in many cases...

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Example (1)

What is the probability of giving birth to twins in Europe?

We can addressing this problem by combining probabilities for different countries in Europe:

$$
P(\text{Twins}) = \sum_{i=1}^{n} P(\text{Twins}|\text{Country}_i) \cdot \frac{N_i}{\sum_{i=1}^{n} N_i}
$$

where N_i is the number off all births in country i

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Total probability of B can be calculated as a sum over probabilities calculated in separate sub-spaces. Very useful in many cases...

Example (2)

What is the probability of producing π^+ in e^+e^- annihilation into Z^0 :

 $e^+e^ \rightarrow Z^0 \rightarrow \pi^+ + ...$

We can divide the sampling space, all Z^0 decays, into separate decay channels, $Z^0\rightarrow f\bar{f},$ where $f = e, \mu, \tau, \nu_e, \nu_\mu, \nu_\tau, u, d, s, c, b$. For some of these channels the answer is known. eg. $P(\pi^+|Z \to \nu\bar{\nu}) = 0$

Bayes' Theorem

For events A and B the two conditional probabilities are related:

$$
P(A|B) = \frac{P(A \cap B)}{P(B)} \quad \text{and} \quad P(B|A) = \frac{P(B \cap A)}{P(A)}
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as $B \cap A = A \cap B$ we obtain: Bayes' Theorem

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This can be also written in a more general form:

$$
P(A_i|B) = \frac{P(B|A_i) P(A_i)}{\sum_{j=1}^{n} P(B|A_j) P(A_j)}
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where A_i is the partition of the sampling space.

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where A_i is the partition of the sampling space. There is nothing new in this as long as A_i and B belong to the same sampling space...

Bayesian approach

Bayes theorem can be used to generalize the concept of probability. In particular, one can consider "probability" of given hypothesis H (theoretical model or model parameter, eg. Hubble constant) when taking into known outcome D (data) of the experiment:

$$
P(H|D) = \frac{P(D|H)}{P(D)} \cdot P(H)
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There are two problems with this approach:

- \bullet H can not be considered an event, sampling space can not be defined (no experiment to repeat)
- \bullet we need to make a subjective assumption about the "prior" $P(H)$ describing our initial belief in hypothesis H

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For these reasons I rather use term "degree of belief" for the result of the Bayesian procedure applied "outside" the sampling space (not to random events)

adapted from G. Cowan, 2011 CERN Summer Student Lectures on Statistics How much should I worry, if I get a positive test result for virus X?

- Hypothesis: $H I$ am infected (I am a carrier of X)
- \bullet Data: D test result is positive

How likely is it that I am a carrier of X, what is $P(H|D)$?

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- \bullet Data: D test result is positive

How likely is it that I am a carrier of X, what is $P(H|D)$?

We need to know efficiency and false rate for the test. Let as assume

 $P(D|H) = 0.99$ test efficiency $P(D|\bar{H}) = 0.01$ false positive rate

We can also assume that 1 person per 1000 is an X carrier in our country

 $P(H) = 0.001$

We first use the total probability theorem to calculate the probability of the positive result:

 $P(D) = P(D|H) \cdot P(H) + P(D|\overline{H}) \cdot P(\overline{H})$ $= 0.99 \cdot 0.001 + 0.01 \cdot 0.999 = 0.01098 \approx 0.011$

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You can believe that your chances of being infected with X are 9% ... How useful is this information in your opinion?

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You can believe that your chances of being infected with X are 9%...

This number represents the probability of person with positive test result being infected.

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You can believe that your chances of being infected with X are 9%...

But this can hardly be interpreted as the probability or your infection (not a random variable)...

Prior problem

Let us look again at the statistical data on the population of Poland:

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We can present it as the age probability (for randomly chosen person). Can we draw any conclusions concerning the life expectation?

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To simplify the problem, let us assume that the "survival probability" does not change in time:

 $p(y|b) = s(a)$

where: b is the year of birth, y is the year of the population census, $a = y - b$ is age.

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Unfortunately, what we measure is the age distribution:

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Unfortunately, what we measure is the age distribution:

 $p(a) = p(b|y)$ for $b = y - a$

We can apply Bayes' Theorem to relate it to the "survival probability"

$$
p(a) = \frac{s(a) \cdot u(y-a)}{\sum_b s(y-b) \cdot u(b)}
$$

where $u(b)$ is the birth number distribution. We need to know it!!!

What is needed is the number of births in each year: shown is my guess

Age structure of the population of Poland (2022) 700 Population [thousands]
29 8 8 8 8
8 9 8 8 8 100 $0\frac{1}{1920}$ 1940 2000 2020 1960 1980 Year of birth

Without exact knowledge of this "prior" we can not draw any conclusions...

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There are also other reasons, why extraction of survival curve from single population census is not possible. In particular, it depends significantly on the year of birth...

Source: [ourworldindata.org](https://ourworldindata.org/life-expectancy)

Concept of probability

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6 [Homework](#page-114-0)

Homework

Bertrand paradox

In a circle of radius R an equilateral triangle is drawn. What is the probability that the length of a random chord is greater than the side of the triangle?

What is, in your opinion, the correct answer to the problem? Give arguments for the proper construction of random chord. You can also propose your own definition/construction!

Solutions should be uploaded until October 16 (Wednesday)